Amrita School of Engineering, Amrita Vishwa Vidyapeetham, Bengaluru 22PHY106- Computational Physics (L-2, T-0, P-3): 3 Credits Odd Semester: 2022-23; B.Tech AIE First Semester

Course Objectives

- The course will lay down the basic concepts and techniques needed for verticals such as robotics.
- It will explore the concepts initially through computational experiments and then try to understand the concepts/theory behind them.
- It will help the students to perceive the engineering problems using the fundamental concepts in physics.
- Another goal of the course is to provide the connection between the concepts of physics, mathematics, and computational thinking.

Course Outcomes (COs)

CO1	Apply the principles of statics to solve elementary problems in physics.
CO2	Apply computational techniques to solve elementary problems in statics.
CO3	Apply computational techniques to solve elementary problems in dynamics.
CO4	Analyze the motion of rigid bodies by applying fundamental principles of dynamics.

Programme Outcomes (POs)

Engineering Knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an
engineering specialization to the solution of complex engineering problems.
Problem Analysis: Identify, formulate, review research literature, and analyze complex engineering problems
reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
Design/Development of Solutions: Design solutions for complex engineering problems and design system
components or processes that meet the specified needs with appropriate consideration for the public health and safety,
and the cultural, societal, and environmental considerations.
Conduct Investigations of Complex Problems: Use research-based knowledge and research methods including
design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid
conclusions.
Modern Tool Usage: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools
including prediction and modeling to complex engineering activities with an understanding of the limitations.
The Engineer and Society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety,
legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.
Environment and Sustainability: Understand the impact of the professional engineering solutions in societal and
environmental contexts, and demonstrate the knowledge of, and need for sustainable development.
Ethics: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering
practice.
Individual and Team Work: Function effectively as an individual, and as a member or leader in diverse teams, and in
multidisciplinary settings.
Communication: Communicate effectively on complex engineering activities with the engineering community and
with society at large, such as, being able to comprehend and write effective reports and design documentation, make
effective presentations, and give and receive clear instructions.
Project Management and Finance: Demonstrate knowledge and understanding of the engineering and management
principles and apply these to one's own work, as a member and leader in a team, to manage projects and in
multidisciplinary environments.
Immultidisciplinary environments. Life-long Learning: Recognize the need for, and have the preparation and ability to engage in independent and life-

Programme Specific Outcomes (PSOs)

PSO1	Have the ability to apply mathematical and analytical techniques to model complex problems.					
PSO2	Have a strong foundation in programming, together with knowledge of modern languages, tools and technologies					
	needed to build secure, robust software systems.					
PSO3	Have the knowledge of AI and ML techniques required for the design and development of intelligent systems to solve					
	real world problems.					

CO-PO Mapping

PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO															
CO1	3	2	-	-	3	-	-	-	2	2	-	2	3	-	-
CO2	3	2	-	-	3	-	-	-	2	2	-	2	3	-	-
CO3	3	2	-	-	3	-	-	-	2	2	-	2	3	-	-
CO4	3	2	2	-	3	-	-	-	2	2	-	2	3	-	1

Syllabus

Unit 1	Newton's Laws of Motion, Force as 3D Vector, Resolution of Forces, Resultant of Forces.						
Unit 2	Equilibrium about a Point, Moment, Couple, Equivalent System, Equilibrium of Rigid Bodies, Degree-of-freedom and						
	Constraints at Supports, Free Body Diagram.						
Unit 3	Kinematics of particles, assumptions, Cartesian, Cylindrical and Spherical frames, and motion of particles in them.						
	Translation and rotation of rigid bodies in 2D – Translation and rotation of rigid bodies in 3D.						
Unit 4	Kinematics of interconnected rigid bodies- Definition of a linkage - Definition of a mechanism -Four-bar						
	mechanism.						

Text Books / References

Beer F.P. and Johnston E.R., Vector Mechanics for Engineers - Volume I - Statics, Volume II - Dynamics, McGraw Hill, New York, 2004.

Meriam J.L and Kraige L.G., Engineering Mechanics, Volume I - statics, Volume 11- dynamics, John Wiley & Sons, New York, 2018.

Hibbeler R. C., Engineering Mechanics: Statics and Dynamics, 11th edition, Pearson Education India, 2017 Saha, S. K., Introduction to Robotics, McGraw-Hill, 2014. Rattan, S. S., Theory of Machines, McGraw-Hill, 2014.

Course Plan

Course I la	11				
Week 1	Introduction to Course Nouton's Louis of Mation Introduction to Vester Alasha				
Week 2	Introduction to Course, Newton's Laws of Motion, Introduction to vector Algebra				
Week 3	Force as Vector, Resolution and Resultant of Forces [Tool: GeoGebra in Labs]				
Week 4	Equilibrium about a point [Tool: GeoGebra]				
Week 5	Equilibrium of Rigid bodies [Tool: GeoGebra]				
Week 6	Desurs of fundom Constraints at Supports (Beams) Free Rody Disgram (Trues Friction etc.)				
Week 7	Degree-of-freedom, Constraints at Supports (Beams), Free Body Diagram (Truss, Friction, etc.)				
Week 8	Vinematics of Derticles [Teel, MATLAD]				
Week 9	Kinematics of Particles [1001: MATLAD]				
Week 10	Vinematics of Divid Dady [Taal, Dake Analyzan UTM Madula]				
Week 11	Kinematics of Rigid Body [1001: RoboAnalyzer, HTM Module]				
Week 12	Vinemetics of Machanisms [Tool: CooCabro and MachAnalyzar]				
Week 13	Kinematics of Mechanishis [1001: GeoGeora and MechAnaryzer]				
Week 14					
Week 15	Analysis of Planar Mechanisms [100]: MAILAB, GeoGebra and MechAnalyzer]				

Proposed Evaluation Scheme

Component	Event Type	Weightage
	Assignments 3: Two Lab Evaluations and One Project (Team of 2 Students)	30%
Internal (709/)	Quizzes 2	20%
(70%)	Mid Term Exam (During T2 of Other Branches)	20%
External	End Semester Exam	30%
(30%)		